

Think big

Heavy payload robot

M-1000iA



USER INTERFACE

Easy integration of services on arm J3



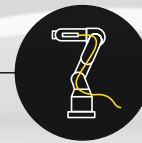
SMOOTH SERIAL LINK DESIGN

Serial link instead of parallel link supports backflip operation on axis J3 for more flexibility and easy integration



STRONG WRIST

Compact design combined with high payload, moment and inertia



CLEAN DESIGN

Clean robot design minimises interferences with peripheral devices



EXCELLENT WEIGHT / PAYLOAD RATIO

5300 kg weight vs. 1000 kg payload



Wide range of J3 arm motion



Biggest serial link robot in FANUC line-up:

- highly suitable for heavy part handling (e.g. EV battery), heavy palletising or packaging and material handling operations
- high payload capacity of 1000 kg
horizontal reach: 3253 mm
vertical reach: 4297 mm
- IP54 at body, IP67 at wrist prepare the robot for all kind of application.
- supports wrist inertia of 840 kgm² and wrist moment 5800 Nm

M-1000iA



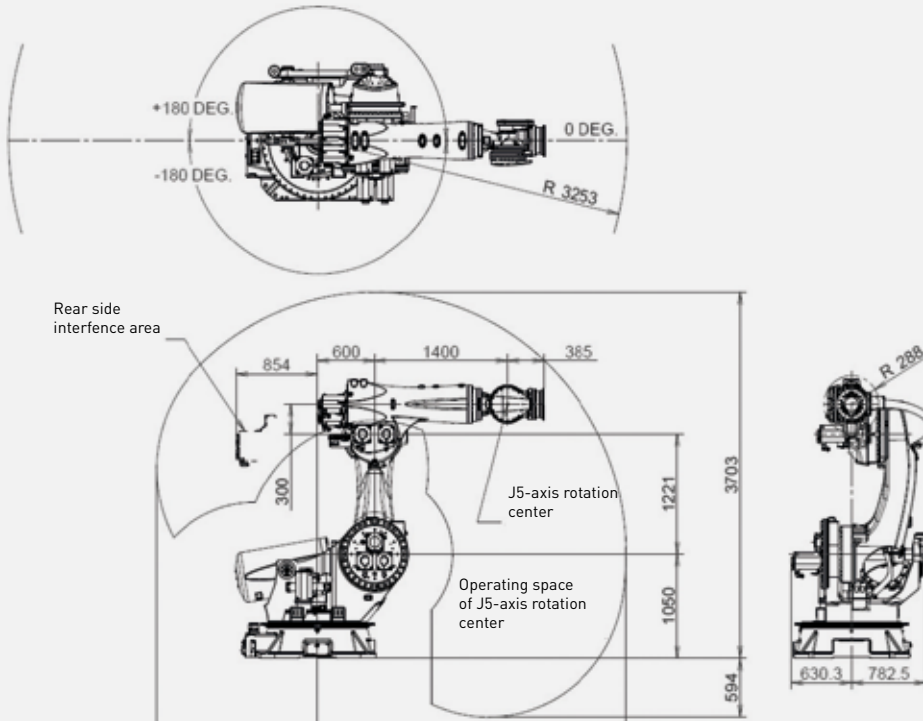
Max. load capacity
at wrist:
1000 kg



Max. reach:
3253 mm

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range (°)						Maximum speed (°/s)						J4 Moment/ Inertia (Nm/kgm ²)	J5 Moment/ Inertia (Nm/kgm ²)	J6 Moment/ Inertia (Nm/kgm ²)
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6			
6	± 0.1	5300	330	145	260	720	240	720	60	50	50	70	70	85	8800/1750	8800/1750	5800/840

Working range



Robot

M-1000iA

Robot footprint [mm]	1350 x 1210
Mounting position Floor	●
Mounting position Upside down	-
Mounting position Angle	-



Controller

R-30iB Plus

Open air cabinet	-
Mate cabinet	-
A-cabinet	●
B-cabinet	○
iPendant Touch	●

Electrical connections

Voltage 50/60Hz 3phase [V]	●
Voltage 50/60Hz 1phase [V]	380-575
Average power consumption [kW]	8

Integrated services

Integrated signals on upper arm In/Out	8/8
Integrated air supply	2

Environment

Acoustic noise level [dB]	-
Ambient temperature [° C]	0-45

Protection

Body standard/optional	IP54
Wrist & J3 arm standard/optional	IP67

● standard ○ on request - not available () with hardware and/or software option